C06RBF - NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

C06RBF computes the discrete Fourier cosine transforms of m sequences of real data values.

2 Specification

SUBROUTINE CO6RBF(M, N, X, WORK, IFAIL)

INTEGER M, N, IFAIL

real X(M*(N+3)), WORK(M*N+2*N+15)

3 Description

Given m sequences of n+1 real data values x_j^p , for $j=0,1,\ldots,n$ and $p=1,2,\ldots,m$, this routine simultaneously calculates the Fourier cosine transforms of all the sequences defined by

$$\hat{x}_k^p = \sqrt{\frac{2}{n}} \left(\frac{1}{2} x_0^p + \sum_{j=1}^{n-1} x_j^p \times \cos\left(jk\frac{\pi}{n}\right) + \frac{1}{2} (-1)^k x_n^p \right), \quad k = 0, 1, \dots, n; \quad p = 1, 2, \dots, m.$$

(Note the scale factor $\sqrt{\frac{2}{n}}$ in this definition.)

Since the Fourier cosine transform is its own inverse, two consecutive calls of this routine will restore the original data.

The transform calculated by this routine can be used to solve Poisson's equation when the derivative of the solution is specified at both left and right boundaries (Swarztrauber [2]).

The routine uses a variant of the fast Fourier transform (FFT) algorithm (Brigham [1]) known as the Stockham self-sorting algorithm, described in Temperton [4], together with pre- and post-processing stages described in Swarztrauber [3]. Special coding is provided for the factors 2, 3, 4 and 5.

4 References

- [1] Brigham E O (1973) The Fast Fourier Transform Prentice-Hall
- [2] Swarztrauber P N (1977) The methods of cyclic reduction, Fourier analysis and the FACR algorithm for the discrete solution of Poisson's equation on a rectangle SIAM Rev. 19 (3) 490–501
- [3] Swarztrauber P N (1982) Vectorizing the FFT's Parallel Computation (ed G Rodrique) Academic Press 51–83
- [4] Temperton C (1983) Fast mixed-radix real Fourier transforms J. Comput. Phys. 52 340–350

5 Parameters

1: M — INTEGER

On entry: the number of sequences to be transformed, m.

Constraint: $M \ge 1$.

2: N — INTEGER

On entry: one less than the number of real values in each sequence, i.e., the number of values in each sequence is n + 1.

Constraint: N > 1.

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3: $X(M*(N+3)) - real \operatorname{array}$

Input/Output

On entry: the data must be stored in X as if in a two-dimensional array of dimension (1:M,0:N+2); each of the m sequences is stored in a **row** of the array. In other words, if the (n+1) data values of the pth sequence to be transformed are denoted by x_j^p , for $j=0,1,\ldots,n$ and $p=1,2,\ldots,m$, then the first m(n+1) elements of the array X must contain the values

$$x_0^1, x_0^2, \ldots, x_0^m, x_1^1, x_1^2, \ldots, x_1^m, \ldots, x_n^1, x_n^2, \ldots, x_n^m$$

The (n+2)th and (n+3)th elements of each row x_{n+2}^p , x_{n+3}^p , for $p=1,2,\ldots,m$, are required as workspace. These 2m elements may contain arbitrary values as they are set to zero by the routine.

On exit: the m Fourier cosine transforms stored as if in a two-dimensional array of dimension (1:M,0:N+2). Each of the m transforms is stored in a **row** of the array, overwriting the corresponding original data. If the (n+1) components of the pth Fourier cosine transform are denoted by \hat{x}_k^p , for $k=0,1,\ldots,n$ and $p=1,2,\ldots,m$, then the m(n+3) elements of the array X contain the values

$$\hat{x}_0^1, \hat{x}_0^2, \dots, \hat{x}_0^m, \hat{x}_1^1, \hat{x}_1^2, \dots, \hat{x}_1^m, \dots, \hat{x}_n^1, \hat{x}_n^2, \dots, \hat{x}_n^m, 0, 0, \dots, 0$$
 (2m times).

4: WORK(M*N+2*N+15) - real array

Workspace

The workspace requirements as documented for this routine may be an overestimate in some implementations. For full details of the workspace required by this routine please refer to the Users' Note for your implementation.

On exit: WORK(1) contains the minimum workspace required for the current values of M and N with this implementation.

5: IFAIL — INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. For users not familiar with this parameter (described in Chapter P01) the recommended value is 0.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors detected by the routine:

IFAIL = 1

On entry, M < 1.

IFAIL = 2

On entry, N < 1.

IFAIL = 3

An unexpected error has occurred in an internal call. Check all subroutine calls and array dimensions. Seek expert help.

7 Accuracy

Some indication of accuracy can be obtained by performing a subsequent inverse transform and comparing the results with the original sequence (in exact arithmetic they would be identical).

8 Further Comments

The time taken by the routine is approximately proportional to $nm \times \log n$, but also depends on the factors of n. The routine is fastest if the only prime factors of n are 2, 3 and 5, and is particularly slow if n is a large prime, or has large prime factors.

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9 Example

This program reads in sequences of real data values and prints their Fourier cosine transforms (as computed by C06RBF). It then calls the routine again and prints the results which may be compared with the original sequence.

9.1 Program Text

```
CO6RBF Example Program Text.
   Mark 19 Release. NAG Copyright 1999.
    .. Parameters ..
   INTEGER
                    NIN, NOUT
   PARAMETER
                    (NIN=5,NOUT=6)
   INTEGER
                   MMAX, NMAX
   PARAMETER
                   (MMAX=5,NMAX=20)
    .. Local Scalars ..
   INTEGER
                    I, IFAIL, J, M, N
   .. Local Arrays ..
   real
                    WORK (MMAX*NMAX+2*NMAX+15), X((NMAX+3)*MMAX)
    .. External Subroutines ..
   EXTERNAL
                    C06RBF
    .. Executable Statements ..
   WRITE (NOUT,*) 'CO6RBF Example Program Results'
   Skip heading in data file
   READ (NIN,*)
20 CONTINUE
   READ (NIN,*,END=120) M, N
   IF (M.LE.MMAX .AND. N.LE.NMAX) THEN
      DO 40 J = 1, M
         READ (NIN,*) (X(I*M+J),I=0,N)
40
      CONTINUE
      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Original data values'
      WRITE (NOUT,*)
      DO 60 J = 1, M
         WRITE (NOUT, 99999) (X(I*M+J), I=0, N)
60
      CONTINUE
      IFAIL = 0
      -- Compute transform
      CALL CO6RBF(M,N,X,WORK,IFAIL)
      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Discrete Fourier cosine transforms'
      WRITE (NOUT,*)
      DO 80 J = 1, M
          WRITE (NOUT,99999) (X(I*M+J),I=0,N)
      CONTINUE
80
       -- Compute inverse transform
      CALL CO6RBF(M,N,X,WORK,IFAIL)
      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Original data as restored by inverse transform'
      WRITE (NOUT,*)
      DO 100 J = 1, M
          WRITE (NOUT,99999) (X(I*M+J),I=0,N)
100
      CONTINUE
```

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```
GO TO 20
ELSE
WRITE (NOUT,*) 'Invalid value of M or N'
END IF
120 CONTINUE
STOP

*
99999 FORMAT (6X,7F10.4)
END
```

9.2 Program Data

```
C06RBF Example Program Data
3 6: Number of sequences, M, (number of values in each sequence)-1, N
0.3854 0.6772 0.1138 0.6751 0.6362 0.1424 0.9562: X, sequence 1
0.5417 0.2983 0.1181 0.7255 0.8638 0.8723 0.4936: X, sequence 2
0.9172 0.0644 0.6037 0.6430 0.0428 0.4815 0.2057: X, sequence 3
```

9.3 Program Results

CO6RBF Example Program Results

Original data values

	0.3854	0.6772	0.1138	0.6751	0.6362	0.1424	0.9562
	0.5417	0.2983	0.1181	0.7255	0.8638	0.8723	0.4936
	0.9172	0.0644	0.6037	0.6430	0.0428	0.4815	0.2057
Discrete Fourier cosine transforms							
	1.6833	-0.0482	0.0176	0.1368	0.3240	-0.5830	-0.0427
	1.9605	-0.4884	-0.0655	0.4444	0.0964	0.0856	-0.2289
	1.3838	0.1588	-0.0761	-0.1184	0.3512	0.5759	0.0110
Original data as restored by inverse transform							

0.3854 0.6772 0.9562 0.1138 0.6751 0.6362 0.1424 0.5417 0.2983 0.1181 0.7255 0.8638 0.8723 0.4936 0.2057 0.9172 0.0644 0.6037 0.6430 0.0428 0.4815

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