#### D02JBF - NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

## 1 Purpose

D02JBF solves a regular linear two-point boundary value problem for a system of ordinary differential equations by Chebyshev-series using collocation and least-squares.

# 2 Specification

```
SUBROUTINE DO2JBF(N, CF, BC, XO, X1, K1, KP, C, IC, W, LW, IW, 1 LIW, IFAIL)

INTEGER N, K1, KP, IC, LW, IW(LIW), LIW, IFAIL

real CF, X0, X1, C(IC,N), W(LW)

EXTERNAL CF, BC
```

# 3 Description

This routine calculates the solution of a regular two-point boundary value problem for a regular linear nth-order system of first-order ordinary differential equations in Chebyshev-series in the range  $(x_0, x_1)$ . The differential equation

$$y' = A(x)y + r(x)$$

is defined by the user-supplied function CF and the boundary conditions at the points  $x_0$  and  $x_1$  are defined by the user-supplied routine BC (see Section 5).

The user specifies the degree of the Chebyshev-series required, K1 - 1, and the number of collocation points, KP. The routine sets up a system of linear equations for the Chebyshev coefficients, n equations for each collocation point and one for each boundary condition. The boundary conditions are solved exactly, and the remaining equations are then solved by a least-squares method. The result produced is a set of coefficients for a Chebyshev-series solution for each component of the solution of the system of differential equations on a range normalised to (-1,1).

E02AKF can be used to evaluate the components of the solution at any point on the interval  $(x_0, x_1)$  – see Section 9 for an example. E02AHF followed by E02AKF can be used to evaluate their derivatives.

#### 4 References

[1] Picken S M (1970) Algorithms for the solution of differential equations in Chebyshev-series by the selected points method *Report Math. 94* National Physical Laboratory

#### 5 Parameters

1: N — INTEGER

On entry: the order of the system of differential equations, n.

Constraint:  $N \ge 1$ .

2: CF - real FUNCTION, supplied by the user.

External Procedure

CF defines the system of differential equations (see Section 3). It must return the value of a coefficient function  $a_{i,j}(x)$ , of A, at a given point x, or of a right-hand side function  $r_i(x)$  if J=0.

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Its specification is:

real FUNCTION CF(I, J, X) INTEGER I, J real X

 $\begin{array}{ll} \textbf{1:} & \textbf{I} - \textbf{INTEGER} \\ \textbf{2:} & \textbf{J} - \textbf{INTEGER} \end{array}$   $\begin{array}{ll} \textit{Input} \\ \textit{Input} \end{array}$ 

On entry: indicate the function to be evaluated, namely  $a_{i,j}(x)$  if  $1 \leq J \leq n$ , or  $r_i(x)$  if J = 0.  $1 \leq I \leq n$ ,  $0 \leq J \leq n$ .

3: X — real Input

On entry: the point at which the function is to be evaluated.

CF must be declared as EXTERNAL in the (sub)program from which D02JBF is called. Parameters denoted as *Input* must **not** be changed by this procedure.

3: BC — SUBROUTINE, supplied by the user.

 $External\ Procedure$ 

BC defines the n boundary conditions, which have the form  $y_k(x_0) = s$  or  $y_k(x_1) = s$ . The boundary conditions may be specified in any order.

Its specification is:

SUBROUTINE BC(I, J, RHS) INTEGER I, J real RHS

1: I — INTEGER Input

On entry: the index of the boundary condition to be defined.

2: J — INTEGER Output

On exit: I must be set to -k if the *i*th boundary condition is  $y_k(x_0) = s$ , or to +k if it is  $y_k(x_1) = s$ .

J must not be set to the same value k for two different values of I.

3: RHS-real

On exit: the value s.

BC must be declared as EXTERNAL in the (sub)program from which D02JBF is called. Parameters denoted as *Input* must **not** be changed by this procedure.

4: X0 - real

5: X1-real Input

On entry: the left- and right-hand boundaries,  $x_0$  and  $x_1$ , respectively.

Constraint: X1 > X0.

6: K1 — INTEGER

On entry: the number of coefficients to be returned in the Chebyshev-series representation of the components of the solution (hence the degree of the polynomial approximation is K1 - 1).

Constraint:  $K1 \ge 2$ .

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7: KP — INTEGER

On entry: the number of collocation points to be used.

Constraint:  $KP \ge K1 - 1$ .

8: C(IC,N) - real array

Output

On exit: the computed Chebyshev coefficients of the kth component of the solution,  $y_k$ ; that is, the computed solution is:

$$y_k = \sum_{i=1}^{\mathrm{K1}} {}'\mathrm{C}(i,k) T_{i-1}(x), \quad 1 \leq k \leq n$$

where  $T_i(x)$  is the *i*th Chebyshev polynomial of the first kind, and  $\sum'$  denotes that the first coefficient, C(1, k), is halved.

9: IC — INTEGER

On entry: the first dimension of the array C as declared in the (sub)program from which D02JBF is called.

Constraint: IC  $\geq$  K1.

10: W(LW) — real array Workspace

11: LW — INTEGER Input

On entry: the dimension of the array W as declared in the (sub)program from which D02JBF is called.

Constraint: LW  $\geq 2 \times N \times (KP+1) \times (N \times K1+1) + 7 \times N \times K1$ .

12: IW(LIW) — INTEGER Workspace

13: LIW — INTEGER

On entry: the dimension of the array IW as declared in the (sub)program from which D02JBF is called.

Constraint: LIW  $\geq$  N  $\times$  (K1+2).

14: IFAIL — INTEGER Input/Output

On entry: IFAIL must be set to 0, -1 or 1. For users not familiar with this parameter (described in Chapter P01) the recommended value is 0.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

# 6 Error Indicators and Warnings

Errors detected by the routine:

 $\mathrm{IFAIL} = 1$ 

$$\begin{array}{ll} {\rm On\ entry}, & {\rm N} < 1, \\ & {\rm or} & {\rm X0} \geq {\rm X1}, \\ & {\rm or} & {\rm K1} < 2, \\ & {\rm or} & {\rm KP} < {\rm K1} - 1, \\ & {\rm or} & {\rm IC} < {\rm K1}. \end{array}$$

IFAIL = 2

On entry, 
$$LW < 2 \times N \times (KP+1) \times (N \times K1+1) + 7 \times N \times K1$$
, or  $LIW < N \times (K1+2)$  (i.e., insufficient workspace).

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IFAIL = 3

Either the boundary conditions are not linearly independent, (that is, in the subroutine BC the variable J is set to the same value k for two different values of I), or the rank of the matrix of equations for the coefficients is less than the number of unknowns. Increasing KP may overcome this latter problem.

IFAIL = 4

The least-squares routine F04AMF has failed to correct the first approximate solution (see F04AMF).

## 7 Accuracy

The Chebyshev coefficients are determined by a stable numerical method. The accuracy of the approximate solution may be checked by varying the degree of the polynomials and the number of collocation points (see Section 8).

### 8 Further Comments

The time taken by the routine depends on the size and complexity of the differential system, the degree of the polynomial solution and the number of matching points.

The collocation points in the range  $(x_0, x_1)$  are chosen to be the extrema of the appropriate shifted Chebyshev polynomial. If KP = K1 - 1, then the least-squares solution reduces to the solution of a system of linear equations and true collocation results.

The accuracy of the solution may be checked by repeating the calculation with different values of K1 and with KP fixed but KP  $\gg$  K1 - 1. If the Chebyshev coefficients decrease rapidly for each component (and consistently for various K1 and KP), the size of the last two or three gives an indication of the error. If the Chebyshev coefficients do not decay rapidly, it is likely that the solution cannot be well-represented by Chebyshev-series. Note that the Chebyshev coefficients are calculated for the range (-1,1).

Linear systems of high order equations in their original form, singular problems, and, indirectly, nonlinear problems can be solved using D02TGF.

# 9 Example

To solve the equation

$$y'' + y = 1$$

with boundary conditions

$$y(-1) = y(1) = 0$$

The equation is written as the first-order system

$$\left(\begin{array}{c}y_1'\\y_2'\end{array}\right) = \left(\begin{array}{cc}0&1\\-1&0\end{array}\right) \left(\begin{array}{c}y_1\\y_2\end{array}\right) + \left(\begin{array}{c}0\\1\end{array}\right)$$

for solution by D02JBF and the boundary conditions are written

$$y_1(-1) = y_1(1) = 0.$$

We use K1 = 4, 6, 8 and KP = 10 and 15, so that the different Chebyshev-series may be compared. The solution for K1 = 8 and KP = 15 is evaluated by E02AKF at nine equally spaced points over interval (-1,1).

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### 9.1 Program Text

**Note.** The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
DO2JBF Example Program Text
  Mark 14 Revised. NAG Copyright 1989.
   .. Parameters ..
                    N, K1MAX, KPMAX, IC, LW, LIW
   INTEGER
  PARAMETER
                    (N=2,K1MAX=8,KPMAX=15,IC=K1MAX,LW=2*N*(KPMAX+1)
                    *(N*K1MAX+1)+7*N*K1MAX,LIW=N*(K1MAX+2))
                    NOUT
   INTEGER.
                    (NOUT=6)
  PARAMETER
   .. Local Scalars ..
  real
                    X, XO, X1
   INTEGER
                    I, IA1, IFAIL, J, K1, KP, M
   .. Local Arrays ..
   real
                    C(IC,N), W(LW), Y(N)
   INTEGER
                    IW(LIW)
   .. External Functions ..
  real
                    CF
  EXTERNAL
                    CF
   .. External Subroutines ..
                   BC, DO2JBF, EO2AKF
  EXTERNAL
   .. Intrinsic Functions ..
   INTRINSIC
                    real
   .. Executable Statements ...
  WRITE (NOUT,*) 'DO2JBF Example Program Results'
  X0 = -1.0e0
  X1 = 1.0e0
  WRITE (NOUT,*)
  WRITE (NOUT,*) ' KP K1
                             Chebyshev coefficients'
  DO 60 KP = 10, KPMAX, 5
      DO 40 K1 = 4, K1MAX, 2
         IFAIL = 1
         CALL DO2JBF(N,CF,BC,XO,X1,K1,KP,C,IC,W,LW,IW,LIW,IFAIL)
         IF (IFAIL.NE.O) THEN
            WRITE (NOUT,99999) KP, K1, ' DO2JBF fails with IFAIL =',
              IFAIL
            STOP
         ELSE
            WRITE (NOUT, 99998) KP, K1, (C(I,1), I=1, K1)
            DO 20 J = 2, N
               WRITE (NOUT, 99997) (C(I, J), I=1, K1)
20
            CONTINUE
            WRITE (NOUT,*)
         END IF
      CONTINUE
40
60 CONTINUE
  K1 = 8
  M = 9
  IA1 = 1
  WRITE (NOUT, 99996) 'Last computed solution evaluated at', M,
  + ' equally spaced points'
  WRITE (NOUT,*)
  WRITE (NOUT, 99995) '
                             X, (J,J=1,N)
  DO 100 I = 1, M
```

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```
X = (X0*real(M-I)+X1*real(I-1))/real(M-1)
        DO 80 J = 1, N
           IFAIL = 0
           CALL EO2AKF(K1,X0,X1,C(1,J),IA1,IC,X,Y(J),IFAIL)
  80
        CONTINUE
        WRITE (NOUT,99994) X, (Y(J),J=1,N)
 100 CONTINUE
     STOP
99999 FORMAT (1X,2(I3,1X),A,I4)
99998 FORMAT (1X,2(I3,1X),8F8.4)
99997 FORMAT (9X,8F8.4)
99996 FORMAT (1X,A,I3,A)
99995 FORMAT (1X,A,2('
                         Y(',I1,')'))
99994 FORMAT (1X,3F10.4)
     END
     real FUNCTION CF(I,J,X)
     .. Parameters ..
     INTEGER
                     (N=2)
     PARAMETER
     .. Scalar Arguments ..
     real
     INTEGER
                     I, J
     .. Local Arrays ..
                     A(N,N), R(N)
     real
     .. Data statements ..
     DATA
             A(1,1), A(2,1), A(1,2), A(2,2)/0.0e0, -1.0e0,
                     1.0e0, 0.0e0/
     DATA
                     R(1), R(2)/0.0e0, 1.0e0/
     .. Executable Statements ..
     IF (J.GT.0) CF = A(I,J)
     IF (J.EQ.0) CF = R(I)
     RETURN
     END
     SUBROUTINE BC(I,J,RHS)
     .. Scalar Arguments ..
     real
                  RHS
     INTEGER
                  I, J
      .. Executable Statements ..
     RHS = 0.0e0
     IF (I.GT.1) THEN
        J = -1
     ELSE
        J = 1
     END IF
     RETURN
     END
```

#### 9.2 Program Data

None.

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### 9.3 Program Results

DO2JBF Example Program Results

```
KP K1
       Chebyshev coefficients
    4 -0.7798 0.0000 0.3899 0.0000
        0.0000 1.5751 0.0000 -0.0629
10
    6 -0.8326 0.0000 0.4253 0.0000 -0.0090 0.0000
        0.0000 1.6290 0.0000 -0.0724 0.0000 0.0009
10
    8 \quad -0.8325 \quad 0.0000 \quad 0.4253 \quad 0.0000 \quad -0.0092 \quad 0.0000 \quad 0.0001 \quad 0.0000
        0.0000 1.6289 0.0000 -0.0724 0.0000 0.0009 0.0000 0.0000
15
    4 -0.7829 0.0000 0.3914 0.0000
        0.0000 1.5778 0.0000 -0.0631
    6 -0.8326 0.0000 0.4253 0.0000 -0.0090 0.0000
15
        0.0000 1.6290 0.0000 -0.0724 0.0000 0.0009
    8 -0.8325 0.0000 0.4253 0.0000 -0.0092 0.0000 0.0001 0.0000
        0.0000 1.6289 0.0000 -0.0724 0.0000 0.0009 0.0000 0.0000
```

Last computed solution evaluated at 9 equally spaced points

X	Y(1)	Y(2)
-1.0000	0.0000	-1.5574
-0.7500	-0.3542	-1.2616
-0.5000	-0.6242	-0.8873
-0.2500	-0.7933	-0.4579
0.0000	-0.8508	0.0000
0.2500	-0.7933	0.4579
0.5000	-0.6242	0.8873
0.7500	-0.3542	1.2616
1.0000	0.0000	1.5574

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