

F08QHF (STRSYL/DTRSYL) – NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

F08QHF (STRSYL/DTRSYL) solves the real quasi-triangular Sylvester matrix equation.

2 Specification

```

SUBROUTINE F08QHF(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C,
1                LDC, SCALE, INFO)
ENTRY          strsyl(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C,
1                LDC, SCALE, INFO)
INTEGER       ISGN, M, N, LDA, LDB, LDC, INFO
real         A(LDA,*), B(LDB,*), C(LDC,*), SCALE
CHARACTER*1   TRANA, TRANB

```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine solves the real Sylvester matrix equation

$$\text{op}(A)X \pm X\text{op}(B) = \alpha C,$$

where $\text{op}(A) = A$ or A^T , and the matrices A and B are upper quasi-triangular matrices in canonical Schur form (as returned by F08PEF (SHSEQR/DHSEQR)); α is a scale factor (≤ 1) determined by the routine to avoid overflow in X ; A is m by m and B is n by n while the right-hand side matrix C and the solution matrix X are both m by n . The matrix X is obtained by a straightforward process of back substitution (see [1]).

Note that the equation has a unique solution if and only if $\alpha_i \pm \beta_i \neq 0$, where $\{\alpha_i\}$ and $\{\beta_i\}$ are the eigenvalues of A and B respectively and the sign (+ or -) is the same as that used in the equation to be solved.

4 References

- [1] Golub G H and van Loan C F (1996) *Matrix Computations* Johns Hopkins University Press (3rd Edition), Baltimore
- [2] Higham N J (1992) Perturbation theory and backward error for $AX - XB = C$ *Numerical Analysis Report* University of Manchester

5 Parameters

1: TRANA — CHARACTER*1 *Input*

On entry: specifies the option $\text{op}(A)$ as follows:

- if TRANA = 'N', then $\text{op}(A) = A$;
- if TRANA = 'T' or 'C', then $\text{op}(A) = A^T$.

Constraint: TRANA = 'N', 'T' or 'C'.

- 2:** TRANB — CHARACTER*1 *Input*
On entry: specifies the option $\text{op}(B)$ as follows:
 if TRANB = 'N', then $\text{op}(B) = B$;
 if TRANB = 'T' or 'C', then $\text{op}(B) = B^T$.
Constraint: TRANB = 'N', 'T' or 'C'.
- 3:** ISGN — INTEGER *Input*
On entry: indicates the form of the Sylvester equation as follows:
 if ISGN = +1, then the equation is of the form $\text{op}(A)X + X \text{op}(B) = \alpha C$;
 if ISGN = -1, then the equation is of the form $\text{op}(A)X - X \text{op}(B) = \alpha C$.
Constraint: ISGN = ± 1 .
- 4:** M — INTEGER *Input*
On entry: m , the order of the matrix A , and the number of rows in the matrices X and C .
Constraint: $M \geq 0$.
- 5:** N — INTEGER *Input*
On entry: n , the order of the matrix B , and the number of columns in the matrices X and C .
Constraint: $N \geq 0$.
- 6:** A(LDA,*) — *real* array *Input*
Note: the second dimension of the array A must be at least $\max(1, M)$.
On entry: the m by m upper quasi-triangular matrix A in canonical Schur form, as returned by F08PEF (SHSEQR/DHSEQR).
- 7:** LDA — INTEGER *Input*
On entry: the first dimension of the array A as declared in the (sub)program from which F08QHF (STRSYL/DTRSYL) is called.
Constraint: $LDA \geq \max(1, M)$.
- 8:** B(LDB,*) — *real* array *Input*
Note: the second dimension of the array B must be at least $\max(1, N)$.
On entry: the n by n upper quasi-triangular matrix B in canonical Schur form, as returned by F08PEF (SHSEQR/DHSEQR).
- 9:** LDB — INTEGER *Input*
On entry: the first dimension of the array B as declared in the (sub)program from which F08QHF (STRSYL/DTRSYL) is called.
Constraint: $LDB \geq \max(1, N)$.
- 10:** C(LDC,*) — *real* array *Input/Output*
Note: the second dimension of the array C must be at least $\max(1, N)$.
On entry: the m by n right-hand side matrix C .
On exit: C is overwritten by the solution matrix X .
- 11:** LDC — INTEGER *Input*
On entry: the first dimension of the array C as declared in the (sub)program from which F08QHF (STRSYL/DTRSYL) is called.
Constraint: $LDC \geq \max(1, M)$.

12: SCALE — *real* *Output*
On exit: the value of the scale factor α .

13: INFO — INTEGER *Output*
On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = $-i$, the i th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO = 1

A and B have common or close eigenvalues, perturbed values of which were used to solve the equation.

7 Accuracy

Consider the equation $AX - XB = C$. (To apply the remarks to the equation $AX + XB = C$, simply replace B by $-B$).

Let \tilde{X} be the computed solution and R the residual matrix:

$$R = C - (A\tilde{X} - \tilde{X}B).$$

Then the residual is always small:

$$\|R\|_F = O(\epsilon) (\|A\|_F + \|B\|_F) \|\tilde{X}\|_F.$$

However, \tilde{X} is **not** necessarily the exact solution of a slightly perturbed equation; in other words, the solution is not backwards stable.

For the forward error, the following bound holds:

$$\|\tilde{X} - X\|_F \leq \frac{\|R\|_F}{sep(A, B)}$$

but this may be a considerable overestimate. See Golub and Van Loan [1] for a definition of $sep(A, B)$, and Higham [2] for further details.

These remarks also apply to the solution of a general Sylvester equation, as described in Section 8.

8 Further Comments

The total number of floating-point operations is approximately $mn(m + n)$.

To solve the **general** real Sylvester equation

$$AX \pm XB = C$$

where A and B are general nonsymmetric matrices, A and B must first be reduced to Schur form (by calling F02EAF, for example):

$$A = Q_1 \tilde{A} Q_1^T \quad \text{and} \quad B = Q_2 \tilde{B} Q_2^T$$

where \tilde{A} and \tilde{B} are upper quasi-triangular and Q_1 and Q_2 are orthogonal. The original equation may then be transformed to:

$$\tilde{A} \tilde{X} \pm \tilde{X} \tilde{B} = \tilde{C}$$

where $\tilde{X} = Q_1^T X Q_2$ and $\tilde{C} = Q_1^T C Q_2$. \tilde{C} may be computed by matrix multiplication; F08QHF (STRSYL/DTRSYL) may be used to solve the transformed equation; and the solution to the original equation can be obtained as $X = Q_1 \tilde{X} Q_2^T$.

The complex analogue of this routine is F08QVF (CTRSYL/ZTRSYL).

9 Example

To solve the Sylvester equation $AX + XB = C$, where

$$A = \begin{pmatrix} 0.10 & 0.50 & 0.68 & -0.21 \\ -0.50 & 0.10 & -0.24 & 0.67 \\ 0.00 & 0.00 & 0.19 & -0.35 \\ 0.00 & 0.00 & 0.00 & -0.72 \end{pmatrix}, B = \begin{pmatrix} -0.99 & -0.17 & 0.39 & 0.58 \\ 0.00 & 0.48 & -0.84 & -0.15 \\ 0.00 & 0.00 & 0.75 & 0.25 \\ 0.00 & 0.00 & -0.25 & 0.75 \end{pmatrix}$$

and

$$C = \begin{pmatrix} 0.63 & -0.56 & 0.08 & -0.23 \\ -0.45 & -0.31 & 0.27 & 1.21 \\ 0.20 & -0.35 & 0.41 & 0.84 \\ 0.49 & -0.05 & -0.52 & -0.08 \end{pmatrix}.$$

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```

*      F08QHF Example Program Text
*      Mark 16 Release. NAG Copyright 1992.
*      .. Parameters ..
INTEGER          NIN, NOUT
PARAMETER       (NIN=5,NOUT=6)
INTEGER          MMAX, NMAX, LDA, LDB, LDC
PARAMETER       (MMAX=8,NMAX=8,LDA=MMAX,LDB=NMAX,LDC=MMAX)
*      .. Local Scalars ..
real           SCALE
INTEGER          I, IFAIL, INFO, J, M, N
*      .. Local Arrays ..
real           A(LDA,MMAX), B(LDB,NMAX), C(LDC,NMAX)
*      .. External Subroutines ..
EXTERNAL        strsyl, X04CAF
*      .. Executable Statements ..
WRITE (NOUT,*) 'F08QHF Example Program Results'
Skip heading in data file
READ (NIN,*)
READ (NIN,*) M, N
IF (M.LE.MMAX .AND. N.LE.NMAX) THEN
*
*      Read A, B and C from data file
*
      READ (NIN,*) ((A(I,J),J=1,M),I=1,M)
      READ (NIN,*) ((B(I,J),J=1,N),I=1,N)
      READ (NIN,*) ((C(I,J),J=1,N),I=1,M)
*
*      Solve the Sylvester equation A*X + X*B = C for X
*
      CALL strsyl('No transpose','No transpose',1,M,N,A,LDA,B,LDB,C,
+           LDC,SCALE,INFO)
*
*      Print the solution matrix X
*
      WRITE (NOUT,*)
      IFAIL = 0
*
      CALL X04CAF('General',' ',M,N,C,LDC,'Solution matrix X',IFAIL)
*
      WRITE (NOUT,*)

```

```

        WRITE (NOUT,99999) 'SCALE = ', SCALE
    END IF
    STOP
*
99999 FORMAT (1X,A,1P,e10.2)
    END

```

9.2 Program Data

```

F08QHF Example Program Data
  4  4                               :Values of M and N
  0.10  0.50  0.68 -0.21
 -0.50  0.10 -0.24  0.67
  0.00  0.00  0.19 -0.35
  0.00  0.00  0.00 -0.72   :End of matrix A
 -0.99 -0.17  0.39  0.58
  0.00  0.48 -0.84 -0.15
  0.00  0.00  0.75  0.25
  0.00  0.00 -0.25  0.75   :End of matrix B
  0.63 -0.56  0.08 -0.23
 -0.45 -0.31  0.27  1.21
  0.20 -0.35  0.41  0.84
  0.49 -0.05 -0.52 -0.08   :End of matrix C

```

9.3 Program Results

F08QHF Example Program Results

```

Solution matrix X
      1      2      3      4
1 -0.4209  0.1764  0.2438 -0.9577
2  0.5600 -0.8337 -0.7221  0.5386
3 -0.1246 -0.3392  0.6221  0.8691
4 -0.2865  0.4113  0.5535  0.3174

SCALE = 1.00E+00

```
