G01NAF - NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

G01NAF computes the cumulants and moments of quadratic forms in Normal variates.

2 Specification

```
SUBROUTINE GO1NAF(MOM, MEAN, N, A, LDA, EMU, SIGMA, LDSIG, L,

RKUM, RMOM, WK, IFAIL)

INTEGER

N, LDA, LDSIG, L, IFAIL

real

A(LDA,N), EMU(*), SIGMA(LDSIG,N), RKUM(L),

RMOM(*), WK(3*N*(N+1)/2+N)

CHARACTER*1

MOM, MEAN
```

3 Description

Let x have a n-dimensional multivariate Normal distribution with mean μ and variance-covariance matrix Σ . Then for a symmetric matrix A, G01NAF computes up to the first 12 moments and cumulants of the quadratic form $Q = x^T A x$. The sth moment (about the origin) is defined as:

$$E(Q^s),$$

where E denotes expectation. The sth moment of Q can also be found as the coefficient of $t^s/s!$ in the expansion of $E(e^{Qt})$. The sth cumulant is defined as the coefficient of $t^s/s!$ in the expansion of $\log(E(e^{Qt}))$.

The routine is based on the routine CUM written by Magnus and Pesaran [4] and based on the theory given by Magnus [1], [2] and [3].

4 References

- [1] Magnus J R (1978) The moments of products of quadratic forms in Normal variables *Statist*. Neerlandica **32** 201–210
- [2] Magnus J R (1979) The expectation of products of quadratic forms in Normal variables: the practice Statist. Neerlandica 33 131–136
- [3] Magnus J R (1986) The exact moments of a ratio of quadratic forms in Normal variables Ann. $\acute{E}conom.$ Statist. 4 95–109
- [4] Magnus J R and Pesaran B (1993) The evaluation of cumulants and moments of quadratic forms in Normal variables (CUM): Technical description *Comput. Statist.* **8** 39–45
- [5] Magnus J R and Pesaran B (1993) The evaluation of moments of quadratic forms and ratios of quadratic forms in Normal variables: Background, motivation and examples Comput. Statist. 8 47–55

5 Parameters

1: MOM — CHARACTER*1

Input

On entry: indicates if moments are computed in addition to cumulants.

If MOM = 'C', only cumulants are computed.

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If MOM = 'M', moments are computed in addition to cumulants.

Constraint: MOM = 'C' or 'M'.

2: MEAN — CHARACTER*1

Input

On entry: indicates if the mean, μ , is zero.

If MEAN = 'Z', μ is zero.

If MEAN = 'M', the value of μ is supplied in EMU.

Constraint: MEAN = 'M' or 'Z'.

3: N — INTEGER

Input

On entry: the dimension of the quadratic form, n.

Constraint: N > 1.

4: A(LDA,N) - real array

Input

On entry: the n by n symmetric matrix A. Only the lower triangle is referenced.

5: LDA — INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which G01NAF is called.

Constraint: LDA \geq N.

6: EMU(*) — real array

Input

Note: the dimension of the array EMU must be at least at least N if MEAN = M, and at least 1 otherwise.

On entry: if MEAN = 'M' EMU must contain the n elements of the vector μ . If MEAN = 'Z', EMU is not referenced.

7: SIGMA(LDSIG,N) — real array

Input

On entry: the n by n variance-covariance matrix Σ . Only the lower triangle is referenced.

Constraint: the matrix Σ must be positive-definite.

8: LDSIG — INTEGER

Input

On entry: the first dimension of the array SIGMA as declared in the (sub)program from which G01NAF is called.

Constraint: LDSIG \geq N.

9: L — INTEGER

Input

On entry: the required number of cumulants, and moments if specified.

Constraint: $1 \le L \le 12$.

10: RKUM(L) - real array

Output

On exit: the L cumulants of the quadratic form.

11: RMOM(*) - real array

Output

Note: the dimension of the array RMOM must be at least L if MOM = M, and at least 1 otherwise.

On exit: if MOM = 'M', the L moments of the quadratic form.

12: WK(3*N*(N+1)/2+N) — *real* array

Work space

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13: IFAIL — INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. For users not familiar with this parameter (described in Chapter P01) the recommended value is 0.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors detected by the routine:

IFAIL = 1

On entry, $N \le 1$, or L < 1,

or L > 12,

or LDA < N,

or LDSIG < N,

or $MOM \neq C'$ or M',

or MEAN \neq 'M' or 'Z'.

IFAIL = 2

On entry, the matrix Σ is not positive-definite.

7 Accuracy

In a range of tests the accuracy was found to be a modest multiple of *machine precision*. See Magnus and Pesaran, [5].

8 Further Comments

None.

9 Example

The example is given by Magnus and Pesaran [5] and considers the simple autoregression:

$$y_t = \beta y_{t-1} + u_t$$
, for $t = 1, 2, ,$

where $\{u_t\}$ is a sequence of independent Normal variables with mean zero and variance one, and y_0 is known. The moments of the quadratic form:

$$Q = \sum_{t=2}^{n} y_t y_{t-1}$$

are computed using G01NAF. The matrix A is given by:

$$A(i+1,i) = \frac{1}{2}$$
 for $i = 1, 2, -1$;

$$A(i,j) = 0$$
 otherwise.

The value of Σ can be computed using the relationships:

$$var(y_t) = \beta^2 var(y_{t-1}) + 1$$

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and

$$cov(y_t y_{t+k}) = \beta cov(y_t y_{t+k-1})$$

for $k \ge 0$ and $var(y_1) = 1$.

The values of β , y_0 , n, and the number of moments required are read in and the moments and cumulants printed.

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
GO1NAF Example Program Text
   Mark 16 Release. NAG Copyright 1992.
    .. Parameters ..
   INTEGER
                     NDIM
   PARAMETER
                    (NDIM=10)
   INTEGER
                    NIN, NOUT
   PARAMETER
                   (NIN=5,NOUT=6)
    .. Local Scalars ..
                     BETA, CON
   real
   INTEGER
                     I, IFAIL, J, L, N
    .. Local Arrays ..
                     A(NDIM, NDIM), EMU(NDIM), RKUM(12), RMOM(12),
   real
                     SIGMA(NDIM, NDIM), WK(3*NDIM*(NDIM+1)/2+NDIM)
    .. External Subroutines ..
   EXTERNAL
                     GO1NAF
    .. Executable Statements ..
   WRITE (NOUT,*) 'GO1NAF Example Program Results'
   Skip heading in data file
   READ (NIN,*)
   READ (NIN,*) BETA, CON
   READ (NIN,*) N, L
   IF (N.LE.NDIM .AND. L.LE.12) THEN
      Compute A, EMU, and SIGMA for simple autoregression
      DO 40 I = 1, N
          DO 20 J = I, N
             A(J,I) = 0.0e0
20
          CONTINUE
      CONTINUE
40
      DO 60 I = 1, N - 1
          A(I+1,I) = 0.5e0
 60
       CONTINUE
      EMU(1) = CON*BETA
      DO 80 I = 1, N - 1
          EMU(I+1) = BETA*EMU(I)
80
      CONTINUE
      SIGMA(1,1) = 1.0e0
      DO 100 I = 2, N
          SIGMA(I,I) = BETA*BETA*SIGMA(I-1,I-1) + 1.0e0
100
       CONTINUE
      DO 140 I = 1, N
          DO 120 J = I + 1, N
             SIGMA(J,I) = BETA*SIGMA(J-1,I)
120
          CONTINUE
140
      CONTINUE
```

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```
IFAIL = 0
         CALL GO1NAF('M', 'M', N, A, NDIM, EMU, SIGMA, NDIM, L, RKUM, RMOM, WK,
                     IFAIL)
         WRITE (NOUT,*)
         WRITE (NOUT,99999) ' N = ', N, ' BETA = ', BETA, ' CON = ', CON
         WRITE (NOUT,*)
         WRITE (NOUT,*) '
                             Cumulants Moments'
         WRITE (NOUT,*)
         DO 160 I = 1, L
            WRITE (NOUT,99998) I, RKUM(I), RMOM(I)
  160
         CONTINUE
      END IF
      STOP
99999 FORMAT (A,I3,2(A,F6.3))
99998 FORMAT (I3,e12.4,4X,e12.4)
      END
```

9.2 Program Data

```
GO1NAF Example Program Data
0.8 1.0 : BETA, CON
10 4 : N, L
```

9.3 Program Results

GO1NAF Example Program Results

```
Cumulants Moments

1 0.1752E+02 0.1752E+02
2 0.3501E+03 0.6569E+03
3 0.1609E+05 0.3986E+05
4 0.1170E+07 0.3404E+07
```

N = 10 BETA = 0.800 CON = 1.000

[NP3390/19/pdf] G01NAF.5 (last)